

# Bounded-Influence Rank Regression

J.D. Naranjo

T.P. Hettmansperger\*

Western Michigan University

Penn State University

June 1992

## Abstract

When  $\varepsilon_i = y_i - x_i'\beta$ , it is known that minimizing  $\sum \sum |\varepsilon_i - \varepsilon_j|$  yields an estimate of regression that attains a bounded *influence of the residual* with 95% efficiency at the normal. We show that introducing weights  $\sum \sum b_{ij} |\varepsilon_i - \varepsilon_j|$  achieves bounded total influence with positive breakdown. Mallows weights in particular are optimal efficient under a predefined bound on the gross error sensitivity. A generalization of Mallows weights allows additional local stability against high leverage points. Two numerical examples illustrate behavior of the estimate.

Key words: Regression; Rank estimate; Bounded-influence; Efficiency; Breakdown; Mallows weights.

## 1 Introduction

Consider the linear regression model  $y_i = \alpha + x_i'\beta + \varepsilon_i, i = 1, \dots, n$  where  $x_i$  is a  $p \times 1$  vector of explanatory variables. In estimating  $\beta$ , the sensitivity of least squares estimates to the effect of outlying observations has led to the development of more robust fitting methods. A general family of rank estimates

---

\*The work of this author was partially supported by ONR Contract N00014-80-C0741.

was proposed by Jaeckel(1972) which achieved some degree of robustness against outliers, while allowing the user a choice of scores for efficiency considerations. The use of Wilcoxon scores in particular has been popular because it achieves good efficiency at the normal error distribution, and robustness against outlying  $y$ -values. However Jaeckel's estimates remained sensitive to observations with outlying  $x$ -values, or high leverage points. Sievers(1983) proposed a weighted rank estimate that reduces to the Wilcoxon under constant weights. In this paper we show that the proposed estimate achieves robustness against both  $x$  and  $y$  outliers (in the sense of bounded-influence). A breakdown point is derived which is a measure of the proportion of outliers that the estimator can handle. Following Krasker(1980), weights are derived which optimize efficiency given a required degree of robustness. Finally, a test is proposed for the hypothesis  $H_0 : \beta' = (\beta'_1, 0')$ .

Two examples in Section 9 illustrate the practical performance of the estimator. In Example 1, a single outlying  $x$ -value makes the least squares and Wilcoxon fits totally unreliable, but the proposed estimator does well. Example 2 fits multiple regression data with three independent variables and multiple outliers. Our estimator with generalized Mallows weights exposes the cluster of high leverage points. This example shows that varying the weight function in order to achieve additional local stability is useful in an exploratory framework. It should be noted that the weights allow the user to control and vary the degree of robustness in  $x$ -space only. Robustness against  $y$ -outliers remains the same as for the Wilcoxon estimator.

This paper contributes to developments in rank-based regression by providing bounded-influence fully iterated estimates. (Tableman(1990) proposed a one-step rank-based estimator). Good efficiency is retained at the normal model (typically 90-95% in simple regression, depending on the distribution of  $x$  and choice of  $c$ ). Finally, the estimate is iterated to convergence and is thus insensitive to estimates of nuisance scale parameters that determine step size.

## 2 The Estimate

Consider estimating  $\beta$  by minimizing

$$D(\beta) = \sum_{i < j} \sum b_{ij} |z_i - z_j| \quad (2.1)$$

where  $z_i = y_i - x_i' \beta$ . The weights  $b_{ij}$  may be a function of the X-matrix. The dispersion function (2.1) was originally proposed by Sievers(1983) in the context of the general linear model. Note that  $D(\beta)$  is free of the intercept  $\alpha$  which may be estimated as a second stage. When  $b_{ij} \equiv 1$ , (2.1) reduces to Jaeckel's(1972) rank dispersion function for Wilcoxon scores

$$D(\beta) = \sum_{i < j} |z_i - z_j| = 2 \sum_{i=1}^n (R(z_i) - (n+1)/2) z_i \quad (2.2)$$

where  $R(z_i)$  is the rank of  $z_i$  among  $z_1 \cdots z_n$ .

The estimate is regression and scale equivariant, and is affine equivariant if  $b_{ij} = b(x_i, x_j)$  is invariant with respect to nonsingular transformations  $Ax_i$ .

We will refer to the estimate as the WPAD (for weighted pairwise absolute deviation).

## 3 Asymptotic Normality

We will treat  $(x_i, y_i), i = 1, \dots, n$  as observations from a  $p + 1$ -dimensional distribution with cdf  $H$ , where  $X$  has marginal cdf  $M(x)$  and the conditional distribution of  $Y$  given  $X$  is denoted  $y|x \sim F(y - \alpha - x' \beta)$ .

Suppose the weights satisfy  $b_{ij} = b_{ji}$ . Create the symmetric  $n \times n$  weight matrix  $W_n = [w_{ij}]$  with off diagonal elements  $w_{ij} = -\frac{1}{n} b_{ij}$  and  $i$ th diagonal  $w_{ii} = \sum_{j \neq i} b_{ij}$ . Let  $X_n^*$  be the  $n \times p$  matrix with  $i$ th row  $x_i, i = 1, \dots, n$  and let  $X_n$  denote the centered  $X_n^*$  matrix. Suppose there exist  $p \times p$  positive definite matrices  $C, V$ , and  $\Sigma$  such that

$$n^{-1} X_n' W_n X_n \xrightarrow{p} C \quad (3.1)$$

$$n^{-1}X_n'W_n^2X_n \xrightarrow{p} V \quad (3.2)$$

$$n^{-1}X_n'X_n \xrightarrow{p} \Sigma \quad (3.3)$$

where  $A \xrightarrow{p} B$  means elementwise convergence in probability. (3.1) and (3.2) are weighted analogues of the more familiar assumption (3.3). Expanding the matrix products shows that

$$\begin{aligned} \Sigma &= (1/2) \int \int (x_2 - x_1)(x_2 - x_1)' dM(x_2)dM(x_1) \\ C &= (1/2) \int \int (x_2 - x_1)(x_2 - x_1)' b(x_1, x_2) dM(x_2)dM(x_1) \\ V &= \int \left[ \int (x_2 - x_1) b(x_2, x_1) dM(x_2) \right] \left[ \int (x_2 - x_1) b(x_2, x_1) dM(x_2) \right]' dM(x_1) \end{aligned}$$

which are all equal if  $b_{ij} \equiv 1$ .

The following theorem is a result from Sievers(1983), extended to the case where  $x$  is random. The extension is proved by conditioning on  $x$  and applying a multivariate version of Slutsky's theorem. In the assumptions from Sievers(1983) which are cited in the theorem, replace *convergence* with *convergence in probability*.

**Theorem 3.1** *Suppose  $\hat{\beta}_n$  minimizes  $D(\beta)$  and let  $\beta_0$  denote the true parameter value. Under Assumptions A1-A3, A6, A7 of Sievers(1983), plus (3.1) and (3.2),*

$$\sqrt{n}(\hat{\beta}_n - \beta_0) \xrightarrow{d} n(0, (1/12\gamma^2)C^{-1}VC^{-1}) \quad (3.4)$$

where  $\gamma = \int f^2(y)dy$ .

The scalar multiple  $(12\gamma^2)^{-1}$  is a measure of scale that is the rank analogue of  $\sigma_f^2 = \int (y - \mu_y)^2 dF(y)$  in the least squares procedure. It is the height of the density of  $(Y_1 - Y_2)$  at the point of symmetry. In the unweighted case  $b_{ij} = 1$ , it can be shown that  $C^{-1}VC^{-1} = \Sigma^{-1}$  so that (3.4) reduces to

$$\sqrt{n}(\hat{\beta}_n - \beta_0) \xrightarrow{d} n(0, (1/12\gamma^2)\Sigma^{-1}) \quad (3.5)$$

similar to the least squares result except for the constant  $(12\gamma^2)^{-1}$ .

## 4 The Influence Function

The influence function is a measure of the sensitivity of an estimator to small changes in the data, and hence is a measure of robustness. More specifically,  $IF(x_o, y_o; H)$  measures approximately  $n$  times the change in the estimator when the point  $(x_o, y_o)$  is added to a very large sample of size  $n - 1$  from the distribution  $H$ .

The gradient vector  $\nabla D(\beta)$  exists almost everywhere and we define

$$\begin{aligned} S(\beta) &= -\nabla D(\beta) \\ &= \sum_{i < j} b_{ij}(x_i - x_j) \text{sgn}(z_i - z_j) \end{aligned} \quad (4.1)$$

where  $x_i$  is a  $p \times 1$  vector and  $\text{sgn}(a) = +1, 0, -1$  as  $a$  is  $>, =, \text{ or } < 0$ . The estimate  $\hat{\beta}$  is a solution to  $S(\beta) = 0$ . (4.1) has asymptotic functional form

$$S(\beta(H)) = \int \int b(x_1, x_2)(x_2 - x_1) \text{sgn}[(y_2 - x_2' \beta) - (y_1 - x_1' \beta)] dH(x_2, y_2) dH(x_1, y_1)$$

and if  $H_n(x, y)$  is the joint empirical cdf then

$$S(\hat{\beta}(H_n)) = 0$$

yields the rank estimate  $\hat{\beta}$ . The following proposition gives the influence function of the estimate  $\hat{\beta}(H_n)$  as defined by Hampel(1974).

**Proposition 4.1** *Suppose that  $\epsilon_i - \epsilon_j$  has density  $g$  continuous at 0 with  $g(0) > 0$ , and (3.1) holds. The influence function of  $\hat{\beta}$  at the model distribution  $H$  in the direction of  $(x_0, y_0)$  is*

$$IF(x_0, y_0) = \frac{F(y_0 - \alpha - x_0' \beta) - 1/2}{\gamma} C^{-1} \int (x_0 - x) b(x_0, x) dM(x) \quad (4.2)$$

The proof is given in the appendix. Note that  $\int (IF)(IF)'$  gives the asymptotic covariance matrix (3.4), as expected. (4.2) is the (asymptotic) average of the columns of the influence matrix in Sievers(1983).

The influence function factors into the *influence of residual* and *influence of position in factor space* (Hampel et al., 1986, p.313), i.e.

$$IF(x_0, y_0) = IR(r_0) \cdot IP(x_0)$$

where  $IR = [F(r_0) - 1/2]/\gamma$  and  $IP = C^{-1} \int (x_0 - x)b(x_0, x)dM(x)$ .  $IR$  is bounded naturally through the error cdf  $F(\cdot)$ .  $IP$  is unbounded in the unweighted case and can be bounded by an appropriate choice of weights.

By equivariance, we can assume without loss of generality that  $Ex = 0$ . If the weights are chosen so that

$$b(x_1, x_2) = h(x_1) \cdot h(x_2) \quad (4.3)$$

and assuming that

$$Exh(x) = 0 \quad (4.4)$$

then  $C = Exx' Eh(x)$  and (4.2) reduces to

$$IF(x_0, y_0) = \gamma^{-1}[F(y_0 - \alpha - x_0'\beta) - 1/2][Exx'h(x)]^{-1}x_0h(x_0). \quad (4.5)$$

Compare (4.5) with the LS influence function

$$IF(x_0, y_0; LS) = (y_0 - \alpha - x_0'\beta)[Exx']^{-1}x_0. \quad (4.6)$$

which is unbounded in both residual and position in factor space.

## 5 The Breakdown Point

The breakdown point, unlike the influence function, measures the effect on the estimator of changes in a large proportion of the sample. If we control a large enough proportion of the sample, we should be able to shift the estimator an arbitrarily large distance from its original value. The breakdown defined below measures the maximum proportion we can control and still not be able to cause an infinitely large shift.

Let  $H_t = (1 - t)H + t\delta_{(x_0, y_0)}$  where  $\delta$  is the cdf of a point mass. Let  $bias(t) = \|\beta(H_t) - \beta(H)\|$ . The breakdown point is defined as  $\epsilon^* = \sup\{t < 1/2 : \max_{x_0, y_0} bias(t) < \infty\}$ . This is a special case of the more general definition by Hampel(1968).

**Theorem 5.1** *Let  $x_1$  and  $x_2$  denote independent random vectors from the marginal distribution  $M$  of the explanatory variables. The estimate  $\hat{\beta}$  has gross-error breakdown*

$$\epsilon^* = \inf_{\|\lambda\|=1} \frac{(1/2)E|\lambda'(x_1 - x_2)|b(x_1, x_2)}{(1/2)E|\lambda'(x_1 - x_2)|b(x_1, x_2) + \sup_{x_0 \in \mathcal{X}} E|\lambda'(x_0 - x)|b(x_0, x)} \quad (5.1)$$

The proof builds upon the proof of Maronna, Bustos and Yohai(1979) and is given in the appendix.

**Corollary 5.1** *Let  $c_p = E|z_1|$  where  $(z_1, \dots, z_p) \sim$  uniform on the sphere  $|z| = 1$ . If  $M(x)$  is such that  $(x_1 - x_2)$  is spherically symmetric and if  $b(x_1, x_2)$  is independent of  $z = (x_1 - x_2) / \|x_1 - x_2\|$ , then*

$$\epsilon^* \geq \frac{(1/2)c_p}{(1/2)c_p + R(p, b, M)} \quad (5.2)$$

where

$$R(p, b, M) = \frac{\sup_{x_0} E \|x_0 - x\| b(x_0, x)}{E \|x_1 - x_2\| b(x_1, x_2)} \quad (5.3)$$

The proof follows from the fact that  $E|\lambda'(x_1 - x_2)|b(x_1, x_2) = c_p E \|(x_1 - x_2)\| b(x_1, x_2)$ .  $c_p$  can be calculated recursively from the relation  $c_p = 2(\pi(p - 1)c_{p-1})^{-1}$  with  $c_1 = 1$  [Maronna, Bustos and Yohai, 1979, p.97].  $R$  depends on the dimension  $p$  and weights  $b$  and weakly on the distribution  $M(x)$ . Suppose  $b$  can be chosen so that  $R \leq k$ , then (5.2) reduces to

$$\epsilon^* \geq \frac{(1/2)c_p}{(1/2)c_p + k} \quad (5.4)$$

Table 1 gives values of the RHS of (5.4) for several values of  $p$  and  $k$ .

**Corollary 5.2**  $\epsilon^* \leq 1/3$ .

Table 1: Lower bounds on  $\epsilon^*$

	p=1	p=2	p=3	p=4	
	2	.20	.14	.11	.10
k	3	.14	.10	.08	.07
	4	.11	.07	.06	.05
	5	.09	.06	.05	.04

The corollary follows from (5.1) and the inequality

$$E|\lambda'(x_1 - x_2)|b(x_1, x_2) \leq \sup_{x_0} E|\lambda'(x_0 - x)|b(x_0, x)$$

for all  $\|\lambda\|=1$ .

## 6 Optimal Robust Weights

In this section we give weights  $h(\cdot)$  that minimize the trace of the asymptotic covariance matrix subject to a bound on the norm of the influence function. By (4.5), the problem reduces to minimizing  $tr[Exx'h(x)]^{-1}Exx'h^2(x)[Exx'h(x)]^{-1}$  given a bound on  $\|xh(x)\|$ . A parallel optimality problem for Mallows GM estimators minimizes  $tr[Exx'h(x)\psi'(r)]^{-1}Exx'h^2(x)\psi^2(r)[Exx'h(x)\psi'(r)]^{-1}$  over  $\psi$  and  $h$  subject to a bound on  $\|xh(x)\psi(r)\|$  (see Hampel et al.,1986, p.321). Following the discussion of Section 6.3 of Hampel et al., we have the following result.

**Theorem 6.1** *Suppose  $F$  has differentiable density  $f$ ,  $\int f^2 < \infty$ , and (3.1), (3.2),(4.3),(4.4) hold. Let  $h_c(x) = \min\{1, c/\|Bx\|\}$  where  $B$  is defined by  $E(xx'h_c(Bx)) = B^{-1}$ . Then  $h_c$  minimizes  $trVar\hat{\beta}$  over all  $h(\cdot)$  that satisfy  $\sup\|IF(x, y)\| \leq d$  ( $= (2\gamma)^{-1} \sup\|Bxh_c(x)\|$ ).*

For applications we suggest a slightly modified but considerably more convenient weight function, as follows. By affine equivariance we may (and should)

standardize the  $x$ 's initially, preferably by some robust location vector  $\mu_x$  and scale matrix  $S_x$ . The  $B$ -matrix in Theorem 6.1 is then close to the identity matrix, and the optimal weights are approximately

$$h(x) = \min \left\{ 1, \frac{c}{[(x - \mu)^t S^{-1}(x - \mu)]^{1/2}} \right\}$$

which are the weights of the regular Mallows GM-estimate.

## 7 Generalized Mallows Weights

“If one point changes the estimate by many standard errors, . . . it is small consolation that the change is bounded by some large number” (Simpson, Ruppert and Carroll (1992)). In the known presence of extreme leverage points, one may choose to focus on achieving this local stability property, giving less consideration to efficiency. In these instances, sensitivity of the estimate to leverage points may be further reduced by using generalized Mallows weights

$$h(x) = \min \left\{ 1, \frac{c}{(x - \mu)^t S^{-1}(x - \mu)} \right\}^{r/2} \quad (7.1)$$

considered by Simpson et al. for their one-step Mallows estimate. See Section 1 of their paper for a discussion on the choice of  $r$ . In an example in Section 9, we show that  $r=2$  is effective in uncovering outliers. We will refer to the estimate using the weights (7.1) as the WPAD( $r$ ). Note that WPAD(1) corresponds to the optimal efficient estimate of the previous section, and WPAD(0) is the regular Wilcoxon rank estimate.

## 8 A Test Based on the Gradient $S(\beta)$

Let  $\beta' = (\beta_1', \beta_2')$  and consider testing  $H_0 : \beta_2 = 0$  versus  $H_a : \beta_2 \neq 0$  where  $\beta_2$  is a  $q \times 1$  vector ( $q \leq p$ ).  $\beta_1$  is a vector of unspecified nuisance parameters. Partition  $S'(\beta) = (S_1'(\beta), S_2'(\beta))$  and let  $\hat{\beta}_0' = (\hat{\beta}_1', 0')$  minimize  $D(\beta)$  over all

$\beta' = (\beta_1', 0')$ . Then  $\hat{\beta}_0$  is a solution to

$$S_1(\hat{\beta}_0) = \frac{d}{d\beta_1} D(\beta) |_{\beta=\hat{\beta}_0} = 0 \quad (8.1)$$

which is a set of  $p - q$  equations in  $p - q$  unknowns. Under the null,  $S(\hat{\beta}_0)$  should be close to the zero vector, where  $S(\cdot)$  is given by (4.1). Thus a test may be constructed that rejects the null hypothesis for values of  $S(\hat{\beta}_0)$  away from zero. By (8.1),  $S(\hat{\beta}_0)' = (S_1'(\hat{\beta}_0), S_2'(\hat{\beta}_0)) = (0', S_2'(\hat{\beta}_0))$  so the test statistic need only depend on  $S_2$ .

Partition  $C =$  according to the partition  $\beta' = (\beta_1', \beta_2')$ .

**Theorem 8.1** *Under the assumptions of Theorem 3.1, if  $H_0 : \beta_2 = 0$  is true, then*

$$G^* = 3n^{-3} S_2'(\hat{\beta}_0) M^{-1} S_2(\hat{\beta}_0) \xrightarrow{d} \chi^2(q)$$

where  $M = [-C_{21}C_{11}^{-1} \ I]V[-C_{21}C_{11}^{-1} \ I]' = V_{22} - V_{21}C_{11}^{-1}C_{12} - C_{21}C_{11}^{-1}V_{12} + C_{21}C_{11}^{-1}V_{11}C_{11}^{-1}C_{12}$ .

See the appendix for proof.

The hypothesis  $H_0 : \beta_2 = 0$  clearly includes tests for main effects, presence of interaction, and significance of covariates, among others. With a proper transformation the hypothesis may include tests for any  $q$  linearly independent constraints on  $\beta$ , i.e.  $H_0 : L\beta = 0$  where  $L$  is a specified  $q \times p$  matrix of constraints.

## 9 Examples

The following examples illustrate robustness of the WPAD estimate to outlying observations with high leverage. The second example shows the usefulness of increased local stability in flagging a high proportion of extreme leverage points.

The weights (7.1) are used in the calculations. For  $(\mu, S)$ , we chose the MVE proposed by Rousseeuw and van Zomeren(1987), i.e., the determinant of

the scale matrix  $S_x$  is minimized subject to

$$\#\{i : (x_i - \mu_x)' S_x^{-1} (x_i - \mu_x) \leq a^2\} \geq h$$

where  $h = [(n + p + 1)/2]$  and  $a^2$  is a constant (taken to be  $a^2 = \chi_{p, .50}^2$ ). The constant  $c$  in (7.1) is set at  $c = \text{med}\{d_i\} + 3\text{MAD}\{d_i\}$  where  $d_i = (x_i - \mu)^t S^{-1} (x_i - \mu)$ . This choice is equivalent to downweighting  $x_i$  whenever  $d_i$  is approximately two standard deviations larger than the mean.

In the simple linear regression case of Example 1, standardization is done using  $(\mu, S) = (\text{med}\{x_i\}, (1.483\text{MAD}\{x_i\})^2)$ .

## 9.1 Pilot-Plant Data

Consider the Pilot-Plant data from Rousseeuw and Leroy (1987), originally from Daniel and Wood(1971). There are 20 observations and one independent variable. Consider the fitted equations for the least squares(LS), Wilcoxon(W) and the WPAD(1). Since the data has no outliers the three fits are quite similar,

$$LS : \hat{y} = 35.5 + .322x$$

$$W : \hat{y} = 35.4 + .323x$$

$$WPAD : \hat{y} = 35.4 + .323x$$

Suppose we introduce an artificial outlier with high leverage (by changing  $x_1 = 123$  to  $x_1 = 1230$ ). The resulting fitted equations are

$$LS : \hat{y} = 65.58 + .0191x$$

$$W : \hat{y} = 65.16 + .0180x$$

$$WPAD : \hat{y} = 35.87 + .3150x$$

While the LS and Wilcoxon estimates have dramatically changed, the WPAD has remained relatively stable. Table 2 shows the effect on the test statistics for testing  $H_0 : \beta = 0$ . Shown are the F-statistic for LS and the gradient test statistics for the Wilcoxon and WPAD. Only the WPAD has unchanged inference results.

Table 2: Test statistic values for  $H_0 : \beta = 0$  (Pilot-Plant data).

	LS	W	WPAD
$x_1 = 123 :$	3381.06*	19.556*	19.556*
$x_1 = 1230 :$	1.770	1.692	16.484*

\* -significant at  $\alpha = .01$

Similar behavior was observed when  $x_1$  was moved even further to  $x_1 = 12300$ . Pursuing another direction, we observed the behavior of the WPAD estimate as more artificial outliers were introduced (by multiplying successive  $x$ -values by 10). The WPAD remained stable up to 3 contaminated points. This exhibits an empirical breakdown of at least 15% for  $p = 3$ .

## 9.2 Hawkins-Bradu-Kass Data

We now look at multiple regression with multiple high-leverage outliers. The artificial data generated by Hawkins, Bradu and Kass(1984) has 75 observations and 3 independent variables. Cases 1-10 are bad leverage points while cases 11-14 are good leverage points, i.e. they agree with the model at the bulk of the data. Table 3 gives selected standardized residuals for the least squares, Wilcoxon, and the WPAD for  $r = 1$  and  $r = 2$ . None of the remaining residuals are larger than 1.4 in absolute value. The LS residuals are externally standardized while the Wilcoxon and WPAD residuals have been standardized according to a first order approximation to  $\sqrt{\text{var}(\hat{\epsilon}_i)}$  proposed by McKean, Sheather and Hettmansperger(1990). Note that the LS, W, and WPAD( $r=1$ ) flag cases 11-14 as outlying, their fits pulled by the ten bad leverage points. At  $r = 2$ , the WPAD has gained additional robustness and flags cases 1-10 instead.

Table 3: Selected standardized residuals for Hawkins data

	LS	W	WPAD(1)	WPAD(2)
1	1.57	0.92	1.97	7.19
2	1.86	1.28	2.23	7.39
3	1.40	0.67	1.97	7.24
4	1.19	-0.35	0.90	6.61
5	1.42	0.34	1.55	7.01
6	1.60	0.85	1.92	7.18
7	2.12	1.84	2.75	7.74
8	1.79	1.49	2.55	7.60
9	1.26	0.04	1.28	6.81
10	1.42	0.71	1.91	7.17
11	-4.03	-13.25	-10.51	0.07
12	-5.29	-15.55	-10.70	0.00
13	-3.04	-12.38	-9.73	0.49
14	-2.67	-11.35	-8.91	-0.03

## 10 Appendix

**Proof of Proposition 4.1:** Let  $\phi(a, b) = 1, 1/2, 0$  as  $a$  is  $<, =,$  or  $> b$ . Then the estimator has asymptotic functional form

$$\int \int x_1 b(x_1, x_2) [\phi(y_2 - y_1 < (x_2 - x_1)' \beta(H)) - 1/2] dH_2 dH_1 = 0.$$

Replace  $H$  by  $H_t = (1 - t)H + t\delta_0$  where  $\delta_0(x, y)$  is the cdf of a point mass at  $(x_0, y_0)$ . Taking derivative of both sides with respect to  $t$  and evaluating at  $t = 0$  gives

$$\begin{aligned} 0 &= (d/dt)|_{t=0} \int \int \int x_1 b(x_1, x_2) [F(y_1 - \alpha - x_1' \beta(H_t) + x_2'(\beta(H_t) - \beta)) - 1/2] \\ &\quad \cdot dF(y_1 - \alpha - x_1' \beta) dM_2 dM_1 + \int x_1 b(x_1, x_2) [F(y_1 - \alpha - x_1' \beta) - 1/2] dM_2 d\delta_0(x_1, y_1) \\ &\quad + \int \int x_1 b(x_1, x_2) [I(y_1 - x_1' \beta > y_2 - x_2' \beta) - 1/2] d\delta_0(x_2, y_2) dH(x_1, y_1) \\ &= \int \int b(x_1, x_2) x_1 (x_2 - x_1)' dM(x_2) dM(x_1) \int f^2(y_1 - \alpha - x_1' \beta) dy_1 \dot{\beta} \\ &\quad + F(y_0 - \alpha - x_0' \beta) \int x_0 b(x_0, x) dM(x) \\ &\quad - [F(y_0 - \alpha - x_0' \beta) - 1/2] \int x b(x, x_0) dM(x) \\ &= -\gamma C \dot{\beta} + [F(y_0 - \alpha - x_0' \beta) - 1/2] \int (x_0 - x) b(x_0, x) dM(x) \end{aligned}$$

where  $\dot{\beta} = (d/dt)\beta(H_t)|_{t=0}$  is the influence function.

**Proof of Theorem 5.1:**

$$\begin{aligned} 0 &= S(\beta(H_t)) \\ &= \int \int (x_1 - x_2) b_{12} [I(y_2 < y_1 + (x_2 - x_1)' \beta(H_t)) - 1/2] dH_t(x_2, y_2) dH_t(x_1, y_1) \\ &= (1 - t)^2 \int \int (x_1 - x_2) b_{12} [I(y_2 < y_1 + (x_2 - x_1)' \beta_t) - 1/2] dH_2 dH_1 \\ &\quad + 2t(1 - t) \int (x_0 - x) b(x_0, x) [I(y < y_0 + (x - x_0)' \beta_t) - 1/2] dH(x, y) \end{aligned}$$

Since the *RHS* sums to 0, the magnitude of the two terms in the sum have to be equal. Thus for every vector  $\lambda \in R^p$  such that  $|\lambda| = 1$ ,

$$2t |E_H \lambda' (x_0 - x) b(x_0, x) [I(y < y_0 + (x - x_0)' \beta_t) - 1/2]| \quad (10.1)$$

$$= (1-t)|E\lambda'(x_1-x_2)b_{12}[I(y_2 < y_1 + (x_2-x_1)'\beta_t) - 1/2]|$$

Now suppose  $\max bias(t) = \infty$ . Then there exists a sequence of point mass distributions  $\{\delta_{0,k}\}$  such that  $\|\beta(H_{t,k})\| \rightarrow \infty$  and  $\lambda_k = \frac{1}{\|\beta(H_{t,k})\|}\beta(H_{t,k}) \rightarrow \lambda^*$  for some  $\lambda^* \in R^p$ . From (10.1)

$$\begin{aligned} & (1-t)|E_{H_2,H_1}\lambda'_k(x_1-x_2)b(x_1,x_2)[I(y_2 < y_1 + (x_2-x_1)'\beta_{t,k}) - 1/2]| \\ &= 2t|E_H\lambda'_k(x_0,k-x)b(x_0,k,x)[I(y < y_0,k + (x-x_0,k)'\beta_{t,k}) - 1/2]| \\ &\leq 2tE_H|\lambda'_k(x_0,k-x)b(x_0,k,x)||1/2| \end{aligned}$$

Taking limits,

$$(1/2)(1-t)E_{H_2,H_1}|\lambda^{*'}(x_1-x_2)|b(x_1,x_2) \leq t \sup_{x_0} E_H|\lambda^{*'}(x_0-x)|b(x_0,x)$$

so that

$$t \geq \frac{(1/2)E_{H_2,H_1}|\lambda'(x_1-x_2)|b(x_1,x_2)}{(1/2)E_{H_2,H_1}|\lambda'(x_1-x_2)|b(x_1,x_2) + \sup_{x_0} E_H|\lambda'(x_0-x)|b(x_0,x)} \quad (10.2)$$

To prove the reverse inequality, suppose  $\max bias(t) < \infty$ . Fix  $x_0$  in (10.1). Take a sequence  $y_{0,k}$  such that  $I(y < y_0 + (x-x_0)'\beta_t) - 1/2 \xrightarrow{P} 1/2$ ,

$$t|E_H\lambda'(x_0-x)b(x_0,x)| \leq (1-t)|E_{H_2,H_1}\lambda'(x_1-x_2)b(x_1,x_2)||1/2|.$$

Take a sequence  $\{x_0\}$  such that  $LHS \rightarrow t \sup_{x_0}|E_H\lambda'(x_0-x)b(x_0,x)|$ ,

$$t \sup_{x_0}|E_H\lambda'(x_0-x)b(x_0,x)| \leq (1/2)(1-t)E_{H_2,H_1}|\lambda'(x_1-x_2)|b(x_1,x_2)$$

**Proof of Theorem 8.1:** We need the following results from Sievers(1983) which we state here as two lemmas. The required assumptions are a subset of the assumptions of Theorem 8.1. Let  $\gamma, C$  and  $V$  be as defined in Section 3,  $B$  be a constant, and suppose  $\beta^*$  denotes the true parameter value.

**Lemma 1 . Asymptotic Linearity**

$$P\left\{ \sup_{\sqrt{n}\|\beta-\beta^*\| \leq B} \|n^{-3/2}S(\beta) - n^{-3/2}S(\beta^*) + 2\gamma\sqrt{n}C(\beta - \beta^*)\| \geq \varepsilon \right\} \rightarrow 0.$$

**Lemma 2**  $n^{-3/2}S(\beta^*) \xrightarrow{d} n(0, (1/3)V)$

Now, under the null  $\beta^{*'} \equiv \beta'_0 = (\beta'_{10}, 0')$ . By Lemma 1, for  $\sqrt{n} \|\beta - \beta^*\| \leq B$ ,

$$n^{-3/2} \begin{bmatrix} S_1(\beta) \\ S_2(\beta) \end{bmatrix} = n^{-3/2} \begin{bmatrix} S_1(\beta_0) \\ S_2(\beta_0) \end{bmatrix} - 2\gamma\sqrt{n} \begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} \begin{pmatrix} \beta_1 - \beta_{10} \\ \beta_2 - 0 \end{pmatrix} + o_p(1).$$

Since  $\sqrt{n}(\hat{\beta}_0 - \beta_0)$  is bounded in probability under the null, substituting  $\hat{\beta}_0$  for  $\beta$  above, we get

$$n^{-3/2}S_1(\hat{\beta}_0) \doteq n^{-3/2}S_1(\beta_0) - 2\gamma\sqrt{n}C_{11}(\hat{\beta}_1 - \beta_{10}) \quad (10.3)$$

$$n^{-3/2}S_2(\hat{\beta}_0) \doteq n^{-3/2}S_2(\beta_0) - 2\gamma\sqrt{n}C_{21}(\hat{\beta}_1 - \beta_{10}) \quad (10.4)$$

By (8.1) and (10.3),  $2\gamma\sqrt{n}(\hat{\beta}_1 - \beta_{10}) \doteq n^{-3/2}C_{11}^{-1}S_1(\beta_0)$ . Substituting in (10.4),

$$\begin{aligned} n^{-3/2}S_2(\hat{\beta}_0) &\doteq n^{-3/2}S_2(\beta_0) - n^{-3/2}C_{21}C_{11}^{-1}S_1(\beta_0) \\ &= n^{-3/2}[-C_{21}C_{11}^{-1} \ I]S(\beta_0) \end{aligned}$$

By Lemma 2,  $\sqrt{3}n^{-3/2}S_2(\hat{\beta}_0) \xrightarrow{d} n(0, M)$ , and the theorem immediately follows.

## References

- [1] Daniel,C. and Wood,F.S. (1971). *Fitting Equations to Data* . John Wiley and Sons, New York.
- [2] Hampel,F.R. (1968). Contributions to the theory of robust estimation. Ph.D. thesis. University of California, Berkeley.
- [3] Hampel,F.R. (1974). The influence curve and its role in robust estimation. *Journal of the American Statistical Association*, 69, 383-393.
- [4] Hampel,F.R., Ronchetti,E.M., Rousseeuw,P.J. and Stahel,W.A. (1986). *Robust Statistics: The Approach Based on Influence Functions*. John Wiley & Sons, New York.

- [5] Hawkins,D.M., Bradu,D. and Kass,G.V. (1984). Location of several outliers in multiple regression data using elemental sets. *Technometrics*, 26, 197-208.
- [6] Heiler,S. (1991). Bounded influence regression using L- and R-type estimates. Report nr. 128/s,Fakultät für Wirtschaftswissenschaften und Statistik, University of Konstanz.
- [7] Hössjer,O. (1991). Rank-based estimates in the linear model with high breakdown point. U.U.D.M. Report 1991:5, Uppsala University.
- [8] Jaeckel,L.A. (1972). Estimating regression coefficients by minimizing the dispersion of residuals. *The Annals of Mathematical Statistics*, 43, 1449-1458.
- [9] Krasker,W.S. (1980). Estimation in linear regression models with disparate data points. *Econometrica*, 48, 1333-1346.
- [10] Maronna,R.A., Bustos,O.H. and Yohai,V.J. (1979). Bias and efficiency-robustness of general M-estimators for regression with random carriers, in *Smoothing Techniques for Curve Estimation*, T. Gasser and M. Rosenblatt (eds.). Lecture Notes in Mathematics 757. Springer, Berlin, 91-116.
- [11] McKean,J.W., Sheather,S.J. and Hettmansperger,T.P. (1990). Regression diagnostics for rank-based methods. *Journal of the American Statistical Association*, 85, 1018-1028.
- [12] Rousseeuw,P.J. and Leroy,A.M. (1987). *Robust Regression and Outlier Detection*. John Wiley and Sons, New York.
- [13] Rousseeuw P.J. and van Zomeren,B.C. (1990). Unmasking multivariate outliers and leverage points (with comments). *Journal of the American Statistical Association*, 85, 633-651.

- [14] Sievers,G.L. (1983). A weighted dispersion function for estimation in linear models. *Communications in Statistics, Theory and Methods*, 12(10), 1161-1179.
- [15] Simpson,D.G., Ruppert,D. and Carroll,R.J. (1992). On one-step GM-estimates and stability of inferences in linear regression. *Journal of the American Statistical Association*, 87, 439-450.
- [16] Tableman,M. (1990). Bounded-influence rank regression: a one-step estimator based on Wilcoxon scores. *Journal of the American Statistical Association*,85, 508-513.